

Reflected BSDE driven by a marked point process with a convex/concave generator

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Reflected BSDEs (RBSDEs)

$$\begin{cases} Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z_s dB_s + K_T - K_t; \\ Y_t \geq L_t, \quad \forall t \in [0, T]. \end{cases} \quad (1)$$

- K is an increasing process, satisfying Skorokhod condition:

$$\int_0^T (Y_t - L_t) dK_t = 0.$$

- El Karoui et al., 1997: arised from pricing of American contingent claims, Lipschitz generator+square integrable terminal;
- Matoussi, 1997: linear growth in (y, z) +square integrable terminal;
- Kobylanski et al., 2002: superlinear in y and quadratic in z + bounded terminal and obstacle;
- Lepeltier and Xu, 2007, Bayraktar and Yao, 2012: unbounded terminal.



Reflected BSDEs with jump (RBSDEJs)

$$\begin{cases} Y_t = \xi + \int_t^T f(s, Y_s, U_s(\cdot)) ds + \int_t^T dK_s - \int_t^T \int_E U_s(e) q(dsde), & 0 \leq t \leq T; \\ Y_t \geq L_t, & 0 \leq t \leq T; \\ \int_0^T (Y_{s-} - L_{s-}) dK_s = 0. \end{cases} \quad (2)$$

- $\tilde{q} = p - \nu$: martingale, (e.g. compensated Poisson process); L : barrier: càdlàg.
- f : Lipschitz in (y, z, u) .
- Generalization in jump process: Hamadène and Ouknine, 2016; Hamadène and Ouknine, 2003: Poisson process; Ren and Otmani, 2010: Lévy process; Crépey and Matoussi, 2008: MPP with bounded density; Foresta, 2021: general MPP.
- Generalization in barrier: Grigorova et al., 2017, 2020: optional process.



Quadratic-Exponential BSDEJs

Generalization in growth condition: Quadratic-Exponential growth:

$$-\frac{\lambda}{2}|z|^2 - \alpha_t - \beta|y| - \frac{1}{\lambda}j_\lambda(t, -u) \leq f(t, y, z, u) \leq \frac{1}{\lambda}j_\lambda(t, u) + \alpha_t + \beta|y| + \frac{\lambda}{2}|z|^2, \quad (3)$$

- $j_\lambda(t, u) = \int_E (e^{\lambda u(e)} - \lambda u(e) - 1) \phi_t(de)$, $\nu(\omega, dt, dx) = \phi_t(\omega, de)dt$.
- Related to the quadratic variation of the Doléans-Dade exponential of the solution.
- BSDEs with bounded terminal: monotone: Becherer, 2006, Morlais, 2010; fixed point: Kazi-Tani et al., 2015.
- Semimartingale viewpoint: Ngoupeyou, 2010, Jeanblanc et al., 2016, El Karoui et al., 2016, existence for unbounded terminal.
- Application in exponential utility maximization in jump market
- Particular form of generator related to utility maximization problem: Kaakai et al., 2022.
- Generalization of classical quadratic BSDEs: Kobylanski, 2000



Assumptions

- (H1) The process A is continuous, with $\|A_T\|_\infty < \infty$. \Rightarrow The MPP is totally inaccessible.
- (H2) The obstacle process L is continuous with $L_T \leq \xi$. \Rightarrow The process K is continuous.
- (H3) For every $\omega \in \Omega$, $t \in [0, T]$, $r \in \mathbb{R}$, the mapping $f(\omega, t, r, \cdot) : L^0(\mathcal{B}(E)) \rightarrow \mathbb{R}$ satisfies: for every $U \in H_V^{2,2}$,

$$(\omega, t, r) \mapsto f(\omega, t, r, U_t(\omega, \cdot))$$

is $\text{Prog} \otimes \mathcal{B}(\mathbb{R})$ -measurable.



Assumption cont.

(d) (Integrability condition) We assume necessarily,

$$\forall p > 0, \quad \mathbb{E} \left[\exp \left\{ p\lambda e^{\beta A_T} (|\xi| \vee L_*^+) + p\lambda \int_0^T e^{\beta A_s} \alpha_s dA_s \right\} \right] < \infty.$$

(e) (Convexity/Concavity condition) For each $(t, y) \in [0, T] \times \mathbb{R}$, $u \in L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$, $u \rightarrow f(t, y, u)$ is convex or concave.



Bounded Lipschitz case

Assume additionally:

- (H4')** (a) There exists a constant $M > 0$ such that $L_* + |\xi| \leq M$, $\mathbb{P} - a.s.$
(b) There exist $L_f \geq 0$, $L_U \geq 0$ such that for every $\omega \in \Omega$, $t \in [0, T]$, $y, y' \in \mathbb{R}$, $u, u' \in L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$ we have

$$|f(\omega, t, y, u(\cdot)) - f(\omega, t, y', u'(\cdot))| \leq L_f |y - y'| + L_U \left(\int_E |u(e) - u'(e)|^2 \phi_t(\omega, de) \right)^{1/2}.$$

- (c) We have

$$\mathbb{E} \left[\int_0^T |f(s, 0, 0)|^2 dA_s \right] < \infty.$$



Bounded Lipchitz case

Theorem 1

Let assumptions (H1), (H2), (H3) and (H4') hold, then,

(i) there exists a solution $(Y, U, K) \in L^2(A) \times H_V^{2,2} \times \mathbb{K}^2$ to (4). Moreover, with the help of Foresta, 2021, Lemma 3.2, $Y \in S^2$.

(ii) If in addition, there exists a positive constant M_0 such that, for each $t \in [0, T]$ and $(y, u) \in \mathbb{R} \times L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$

$$|f(t, y, u)| \leq M_0.$$

Then, there exists a unique solution $(Y, U, K) \in S^\infty \times J^\infty \times \mathbb{K}^2$.

Need better uniform estimations in the sequel. $H_V^{2,p}$ is the space of predictable

processes U such that $\|U\|_{H_V^{2,p}} := \left(\mathbb{E} \left[\int_{[0,T]} \int_E |U_s(e)|^2 \phi_s(de) dA_s \right]^{\frac{p}{2}} \right)^{\frac{1}{p}} < \infty$.



Comparison theorem

Theorem 2

Let $(\xi, f, L), (\hat{\xi}, \hat{f}, \hat{L})$ be two parameter sets and let (Y, U, K) (resp. $(\hat{Y}, \hat{U}, \hat{K})$) be a solution of $RBSDE(\xi, f, L)$ (resp. $RBSDE(\hat{\xi}, \hat{f}, \hat{L})$) such that \mathbb{P} -a.s., $\xi \leq \hat{\xi}$ and that $L_t \leq \hat{L}_t$ for any $t \in [0, T]$. For process α and constants $\beta, \tilde{\beta} \geq 0, \lambda > 0$, suppose (H1)-(H2) and (H4)(d) hold, $Y, \hat{Y} \in \mathcal{E}, U, \hat{U} \in H_v^{2,p}$ and $K, \hat{K} \in \mathbb{K}^p$, for each $p \geq 1$. If in addition either of the following two holds:

- (i) f satisfies (H3), (H4)(a-b), f is convex in u , $\Delta f(t) := f(t, \hat{Y}_t, \hat{U}_t) - \hat{f}(t, \hat{Y}_t, \hat{U}_t) \leq 0$, $dt \otimes d\mathbb{P}$ -a.e., and $f(t, y, u) \leq \alpha_t + \beta|y| + \frac{1}{\lambda}j_\lambda(t, u)$;
- (ii) \hat{f} satisfies (H3), (H4)(a-b), \hat{f} is convex in u , $\Delta f(t) := f(t, Y_t, U_t) - \hat{f}(t, Y_t, U_t) \leq 0$, $dt \otimes d\mathbb{P}$ -a.e., and $\hat{f}(t, y, u) \leq \alpha_t + \beta|y| + \frac{1}{\lambda}j_\lambda(t, u)$;

then it holds \mathbb{P} -a.s. that $Y_t \leq \hat{Y}_t$ for any $t \in [0, T]$.

Comparison theorem

- The θ -method; Fix $\theta \in (0, 1)$., set $\tilde{Y} := Y - \theta\hat{Y}$, $\tilde{U} := U - \theta\hat{U}$;
- To deal with j term: define

$$a_t := \mathbf{1}_{\{Y_t \geq 0\}} \left(\mathbf{1}_{\{Y_t \neq \hat{Y}_t\}} \frac{\mathfrak{F}(t, Y_t, \hat{U}_t) - \mathfrak{F}(t, \hat{Y}_t, \hat{U}_t)}{Y_t - \hat{Y}_t} - \tilde{\beta} \mathbf{1}_{\{Y_t = \hat{Y}_t\}} \right) - \tilde{\beta} \mathbf{1}_{\{Y_t < 0 \leq \hat{Y}_t\}}$$

$$+ \mathbf{1}_{\{Y_t \vee \hat{Y}_t < 0\}} \left(\mathbf{1}_{\{\tilde{Y}_t \neq 0\}} \frac{\mathfrak{F}(t, Y_t, U_t) - \mathfrak{F}(t, \theta\hat{Y}_t, U_t)}{\tilde{Y}_t} - \tilde{\beta} \mathbf{1}_{\{\tilde{Y}_t = 0\}} \right), \quad t \in [0, T],$$

and $\tilde{A}_t := \int_0^t a_s dA_s$, $t \in [0, T]$, estimate the exponential transform

$$\Gamma_t := \exp \left\{ \zeta_\theta e^{\tilde{A}_t} \tilde{Y}_t \right\}, \quad \text{where } \zeta_\theta := \frac{\lambda e^{\tilde{\beta} \|A_T\|_\infty}}{1 - \theta}.$$



Comparison theorem

- Plug in suitable estimations for K .
-

$$Y_t - \theta \widehat{Y}_t \leq \frac{1 - \theta}{\lambda} \ln \left(1 \vee \frac{\lambda e^{\tilde{\beta} \|A_T\|_\infty}}{1 - \theta} \right) e^{-\tilde{\beta} \|A_T\|_\infty - \tilde{A}_t} \\ + \frac{1 - \theta}{\lambda} \left(e^{\tilde{\beta} \|A_T\|_\infty} + \ln (\mathbb{E} [\eta (1 + K_T) \mid \mathcal{G}_t]) \right) e^{-\tilde{\beta} \|A_T\|_\infty - \tilde{A}_t}, \quad \mathbb{P}\text{-a.s.}$$

- We get rid of A_γ condition: $\gamma > -1$,

$$f(t, y, z, u) - f(t, y, z, u') \leq \int_E \gamma_t(x) (u - u')(x) \psi_t(dx).$$



A priori estimates

Definition 3 (Solution to the RBSDE)

Under assumptions (H1)-(H4), a solution to RBSDE (4) is a triple process (Y, U, K) on $[0, T]$, in which Y is a càdlàg process, and U is an \mathbb{G} -predictable random field. Moreover, for each $p \geq 1$, processes $\int_0^\cdot \int_E (e^{p\lambda U_t(e)} - 1) q(dsde)$ and $\int_0^\cdot \int_E (e^{p\lambda U_t(e)} - 1) q(dsde)$ are local martingales on $[0, T]$. K is a continuous increasing process.

The following additional assumption helps provide uniform estimates for the solutions.

(H5) (Uniform linear bound condition) There exists a positive constant C_0 such that for each $t \in [0, T]$, $u \in L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$, if f is convex (resp. concave) in u , then $f(t, 0, u) - f(t, 0, 0) \geq -C_0 \|u\|_t$ (resp. $f(t, 0, u) - f(t, 0, 0) \leq C_0 \|u\|_t$).

Weaker than the A_γ condition.



A priori estimates for Y

Bounded obstacle and terminal first (+ monotone convergence \Rightarrow unbounded).

Proposition 4

Let (ξ, f, L) be a parameter set such that (H1'), (H2)-(H3), (H4)(b-e), (H4')(a) and (H5) hold. If $(Y, U, K) \in \mathcal{E} \times H^{2,p} \times \mathbb{K}^p$, for each $p \geq 1$, is a solution of the quadratic exponential RBSDE (ξ, f, L) , then it holds \mathbb{P} -a.s. that for each $t \in [0, T]$,

$$\exp \{p\lambda|Y_t|\} \leq \mathbb{E}_t \left[\exp \left\{ p\lambda e^{\beta A_T} (|\xi| \vee L_*^+) + p\lambda \int_t^T e^{\beta A_s} \alpha_s dA_s \right\} \right]. \quad (7)$$

By estimations for BSDEs (see our work Gu et al., 2024) and Snell envelope.



A priori estimates for U and K

Proposition 5

Let (ξ, f, L) be a parameter such that (H1)-(H4) hold. If (Y, U, K) is a solution of the quadratic RBSDE (ξ, F, L) such that $Y \in \mathcal{E}$, then for each $p \geq 1$,

$$\mathbb{E} \left[\left(\int_0^T \int_E |U_t(e)|^2 \phi_t(de) dA_t \right)^{\frac{p}{2}} + K_T^p \right] \leq C_p \mathbb{E} \left[e^{36p\lambda(1+\beta\|A_T\|_\infty)Y_*} \right] < \infty, \quad (8)$$

and also

$$\mathbb{E} \left[\int_0^T \int_E \left(e^{p\lambda|U_t(e)|} - 1 \right)^2 \phi_t(de) dA_t \right] \leq C_p \mathbb{E} \left[e^{36p\lambda(1+\beta\|A_T\|_\infty)Y_*} \right] < \infty, \quad (9)$$

where C_p is a constant depending on p and the constants in (H1)-(H4).



A priori estimates for U and K

- 1 Estimate the quadratic variation of $\underline{G}_t = -Y_t + \int_0^t \alpha_s dA_s + \int_0^t \beta |Y_s| dA_s$ via Garcia-Neveu Lemma.
- 2 Estimate $\mathbb{E}[K_T^2]$ via Burkholder-Davis-Gundy inequality. Not easy to obtain $\mathbb{E}[K_T^p]$ directly without adequate integrability on U at this stage.
- 3 Define similarly $\bar{G}_t = Y_t + \int_0^t \alpha_s dA_s + \int_0^t \beta |Y_s| dA_s$, estimate the quadratic variation of $e^{p\lambda\bar{G}_t}$ via Garcia-Neveu Lemma. Need the previous estimation on K .
- 4 Obtain adequate integrability for U from 1 and 3.
- 5 Estimate $\mathbb{E}[K_T^p]$ via a generalized Burkholder-Davis-Gundy inequality (see Hernández-Hernández and Jacka, 2022, Theorem 2.1).



Existence

Theorem 6 (Existence)

Assume that assumptions (H1)-(H5) are fulfilled. Then the RBSDE (4) admits a unique solution $(Y, U, K) \in \mathcal{E} \times H^{2,p} \times \mathbb{K}^p$, for all $p \geq 1$.

- \mathcal{E}^p : $e^{|Y|} \in S^p$. Denote $Y \in \mathcal{E}$ if $Y \in \mathcal{E}^p$ for any $p \geq 1$.
- $H_v^{2,p}$: predictable processes U such that

$$\|U\|_{H_v^{2,p}} := \left(\mathbb{E} \left[\int_{[0,T]} \int_E |U_s(e)|^2 \phi_s(de) dA_s \right]^{\frac{p}{2}} \right)^{\frac{1}{p}} < \infty.$$

- $\mathbb{K} \subset \mathbb{C}^0$: increasing and continuous adapted process starting from 0, $\mathbb{K}^p \subset \mathbb{K}$:
 $X \in \mathbb{K}^p \Leftrightarrow X_T \in \mathbb{L}^p$.
- Begin with bounded case and then generalize to unbounded case.



Existence–bounded terminal and obstacle

We use the following auxiliary generators to approximate **convex** f .

$$f^n(t, y, u) = \inf_{r \in L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))} \{f(t, y, r) + n\|u - r\|_t\}.$$

The properties of the auxiliary drivers are outlined below. See also Lepeltier and Martin, 1997.

Lemma 7

Under the assumptions (H1)–(H4),

*(i) The sequence $\{f^n\}_n$ is **globally Lipschitz** with respect to (y, u) in $\mathbb{R} \times L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$.*

*(ii) The sequence $\{f^n\}_n$ is **convex** with respect to u if f is convex with respect to u for $u \in L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$.*

*(iii) For $t \in [0, T]$, the sequence $\{f^n\}_n$ **converges to f** on $(y, u) \in \mathbb{R} \times L^2(E, \mathcal{B}(E), \phi_t(\omega, dy))$*

Also strong convergence on bounded subsets.



Existence–bounded terminal and obstacle

Lemma 7 cont.

(iv) For $n > C_0$, (Here we need the linear lower bound assumption for the lower bound.)

$$\begin{aligned} -3\alpha_t - 3\beta|y| - \frac{1}{\lambda}j_\lambda(t, -u) &\leq f^n(t, y, u) \\ &\leq f(t, y, u) \leq \alpha_t + \beta|y| + \frac{1}{\lambda}j_\lambda(t, u) \leq 3\alpha_t + 3\beta|y| + \frac{1}{\lambda}j_\lambda(t, u). \end{aligned} \tag{10}$$

(v) For each $n > C_0$ and $t \in [0, T]$, $f^n(t, 0, 0) = f(t, 0, 0)$.



Existence–bounded terminal and obstacle

The proof consists of 5 steps. We start from RBSDE $(\xi, f^{n,k}, L)$, where $n > C_0$, $f^{n,k} = (f^n \wedge -k) \vee k$, $k \in \mathbb{N}$. $(Y^{n,k}, U^{n,k}, K^{n,k}) \in \mathcal{S}^\infty \times \mathcal{J}^\infty \times \mathbb{K}^2$.

Step 1 The convergence of the sequence $\{(Y^{n,k}, U^{n,k})\}_k$ to (Y^n, U^n) .

- For fixed $n > C_0$, $\lim_{k \rightarrow \infty} \mathbb{E} \left[|Y_t^n - Y_t^{n,k}|^2 \right] = 0$,
- $\lim_{k \rightarrow \infty} \mathbb{E} \left[\int_0^T \int_E |U^{n,k} - U^n|^2 \phi_t(de) dA_t \right] = 0$.
- Stochastic (pointwise) Gronwall inequality involved a martingale term (inspired by Scheutzwow, 2013, Theorem 4.)
- To obtain uniform a priori estimates for RBSDE (ξ, f^n, L) .

Step 2 Construction of candidate solution (Y^0, U^0) .

- For Y^0 , comparison theorem.
- For U^0 , stability of Cauchy sequence.
- Based on uniform a priori estimates.
- Y^0 not for sure càdlàg, only a limit for strong convergence in constructing U^0 .



Existence–bounded terminal and obstacle

Step 3 A priori estimate of $|Y^n - Y^m|$.

- The θ -method.
-

$$|Y_t^n - Y_t^m| \leq (1 - \theta) (|Y_t^m| + |Y_t^n|) + \frac{1 - \theta}{\lambda} \ln \left(\sum_{i=1}^3 J_t^{m,n,i} \right), \quad t \in [0, T],$$

$J^{m,n,i}$ uniformly bounded in appropriate spaces.

Step 4 Convergence of the sequence $\{Y^n\}$ in S^1 .

- Find a càdlàg candidate \tilde{Y}^0 .
- Need the estimate in step 3.

Step 5 Find candidate solution K^0 and verify the solution (\tilde{Y}^0, U^0, K^0) .

- For K^0 , Cauchy sequence in S^2 .



Existence–unbounded terminal and obstacle

Approximate by solutions in bounded case, i.e., $\text{RBSDE}(\xi^n, \bar{f}^n, L^n)$ with solution $(Y^n, U^n, K^n) \in \mathcal{E} \times \cap_{p \geq 1} H_\nu^{2,p} \times \cap_{p \geq 1} \mathbb{K}^p$. Here, $\xi^n = (\xi \wedge n) \vee -n$, $L^n = (L \wedge n) \vee -n$, $\bar{f}^n(t, \cdot, \cdot) = f(t, \cdot, \cdot) - f(t, 0, 0) + f^n(t, 0, 0)$, $f^n(t, 0, 0) = (f(t, 0, 0) \wedge n) \vee -n$.

Step 1 Construction of candidate solution Y^0 .

- Find an a priori estimate of $|Y^n - Y^m|$ (solutions for truncated RBSDEs) via the θ -method.
- Some tricks when separating different obstacles.

Step 2 Construction of candidate solution U^0 .

- Cauchy sequence in $H_\nu^{2,2}$.
- A priori estimates in $H_\nu^{2,p}$.

Step 3 Construction of candidate solution K^0 and verification of the solution (Y^0, U^0, K^0) .

- Cauchy sequence in \mathbb{K}^2 .
- A priori estimates in \mathbb{K}^p .



Generalization to quadratic-exponential RBSDEs (involving Z)

$$\begin{cases} Y_t = \xi + \int_t^T f(s, Y_s, Z_s, U_s) dC_s + \int_t^T dK_s - \int_t^T Z_s dB_s - \int_t^T \int_E U_s(e) q(dsde), & 0 \leq t \leq T, \\ Y_t \geq L_t, & 0 \leq t \leq T, \\ \int_0^T (Y_{s-} - L_{s-}) dK_s = 0, & \mathbb{P}\text{-a.s.} \end{cases} \quad (11)$$

With quadratic-exponential growth condition:

$$\begin{aligned} & - \left(\alpha_t + \beta|y| + \frac{\lambda}{2}|z|^2 \right) dt + \left(-\alpha_t - \beta|y| - \frac{1}{\lambda} j_\lambda(t, -u) \right) dA_t \\ & \leq f(t, y, z, u) dC_t \leq \left(\alpha_t + \beta|y| + \frac{1}{\lambda} j_\lambda(t, u) \right) dA_t + \left(\alpha_t + \beta|y| + \frac{\lambda}{2}|z|^2 \right) dt. \end{aligned} \quad (12)$$

Combining our discussion with the wellposedness of quadratic RBSDEs in Bayraktar and Yao, 2012 to conclude.



Application: American contingent claims pricing via utility maximization

- Risky asset:

$$dS_s = S_{s-} \left(b_s ds + \sigma_s dW_s + \int_{\mathbb{R} \setminus \{0\}} \beta_s(x) \tilde{N}_p(ds, dx) \right),$$

- Exponential utility function: $U_{\tilde{\alpha}}(\cdot) := -\exp(-\tilde{\alpha}\cdot)$
- Value process:

$$V_t^B(x) = \sup_{\pi \in A_t} \mathbb{E} \left(U_{\tilde{\alpha}} \left(x + \int_t^T \pi_s \frac{dS_s}{S_{s-}} - B \right) \mid \mathcal{G}_t \right). \quad (13)$$



Connection with quadratic-exponential RBSDEs

$$V_t^B(x) = -\exp(-\tilde{\alpha}(x - Y_t)),$$

where Y_t is the first component of the solution (Y, Z, U) of the BSDE:

$$Y_t = B + \int_t^T f_s(Z_s, U_s) ds - \int_t^T Z_s dW_s - \int_t^T \int_{\mathbb{R} \setminus \{0\}} U_s(x) \tilde{N}_p(ds, dx), \quad 0 \leq t \leq T, \quad \mathbb{P}\text{-a.s.}$$

$$f(s, z, u) = \inf_{\tilde{\pi} \in \mathcal{C}} \left(\frac{\tilde{\alpha}}{2} \left| \tilde{\pi} \sigma_s - \left(z + \frac{\theta}{\tilde{\alpha}} \right) \right|^2 + \frac{1}{\tilde{\alpha}} j_{\tilde{\alpha}}(s, u - \tilde{\pi} \beta_s) \right) - \theta z - \frac{|\theta|^2}{2\tilde{\alpha}}.$$

There exists $\pi^* \in A_t$ (compact) satisfying:

$$\pi_s^* \in \arg \min_{\tilde{\pi} \in \mathcal{C}} \left(\frac{\tilde{\alpha}}{2} \left| \tilde{\pi} \sigma_s - \left(Z_s + \frac{\theta_s}{\tilde{\alpha}} \right) \right|^2 + \frac{1}{\tilde{\alpha}} j_{\tilde{\alpha}}(s, U_s - \tilde{\pi} \beta_s) \right).$$



Pricing for American contingent claims

- As in Rouge and El Karoui, 2000, the price of contingent claim B defined via utility function reads:

$$pr_t(B) = \inf\{y \in \mathbb{R}, V_t^B(y) \geq V_t^0(0) = -1\} = Y_t := Y_t(T, B).$$

- With early exercise payoff: $\{\xi_t, 0 \leq t \leq T\}$, the price

$$Y_t^A = \text{ess sup}_{\tau \in \mathcal{S}'_{t,T}} Y_t(\tau, \xi_\tau).$$

satisfies the RBSDE:

$$\begin{cases} Y_t^A = B + \int_t^T f(s, Z_s, U_s) ds - \int_t^T Z_s dW_s - \int_t^T \int_{\mathbb{R} \setminus \{0\}} U_s(x) \tilde{N}_p(ds, dx) + \int_t^T dK_s; \\ Y_t^A \geq \xi_t; \\ \int_0^T (Y_{s^-}^A - \xi_s) dK_s = 0, \quad \mathbb{P}\text{-a.s.}, \end{cases} \quad (14)$$

in which f satisfies all aforementioned assumptions.



Thank You